

Computer Programs to Analyze Stability of Slopes Containing Piles

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SYNOPSIS : Piles have been used as one of the most common measures to ensure the stability of unstable slopes. Considering the arching effect in soil between piles, a technique was presented to analyze the stability of slopes containing piles. It is emphasized in the analysis that both the slope-stability and the pile-stability should be ensured at the same time to capture the whole stability of slopes containing piles. A design method was established in 1981 by the author on the basis of the analysis method of the slope containing piles. Computer programs, SPILE and CHAMP, were made to analyze and design the slope containing piles. SPILE can be used to design the stabilizing piles, while CHAMP can be used to analyze the behavior of foundation piles for bridge abutments. The limit equilibrium method for infinite slope is applied in SPILE, while the limit equilibrium method based on slice method proposed by Fellenius is applied in CHAMP.

A new computer program SLOPILE is presented in this study to analyze the stability of slopes containing piles. The analytical techniques applied in SPILE and CHAMP are also applied in SLOPILE, so that wide application could be provided. Therefore, SLOPILE can calculate the slope stability for both planar failure surfaces in infinite slopes and arc failure surfaces based on Fellenius and Bishop simplified methods. OS system combined Dos and CAD, which is applied in SPILE and CHAMP, is improved to Windows version. SLOPILE can be used to analyze and design piles installed in not only fill slopes but also cut slopes. SLOPILE can be also used to analyze the behavior of foundation piles for bridge abutments constructed on soft grounds.

Key words : slope stability, stabilizing pile, lateral earth pressure, computer program, slope stability analysis.

1.

CHAMP SPILE CHAMP
 (Fellenius) SPILE
 SPILE CHAMP
 가 Bishop 가 (SLOPILE)
 Dos CAD OS
 Windows
 SLOPILE , SLOPILE

2.
2.1

(Passive pile)
(, 1983).
가 가
가 (福本, 1977; Ito, Matsui and Hong, 1981, 1982).

가
(福本, 1977).
(, 1982, 1983, 1984a, 1984b, 1984c; Matsui, Hong and Ito, 1982).
(Ito, Matsui and Hong, 1981, 1982)
(Hong, 1986).

가 (2, 1987; 4, 1987; 3, 1989).
2.1 H-300×300
1.5m 2 3m

2.2

()
3



2.2.1

()

가

2.2.2

2

가

가

가

가

가 가

가

가

가

3.

2가

3.1

2

(

)

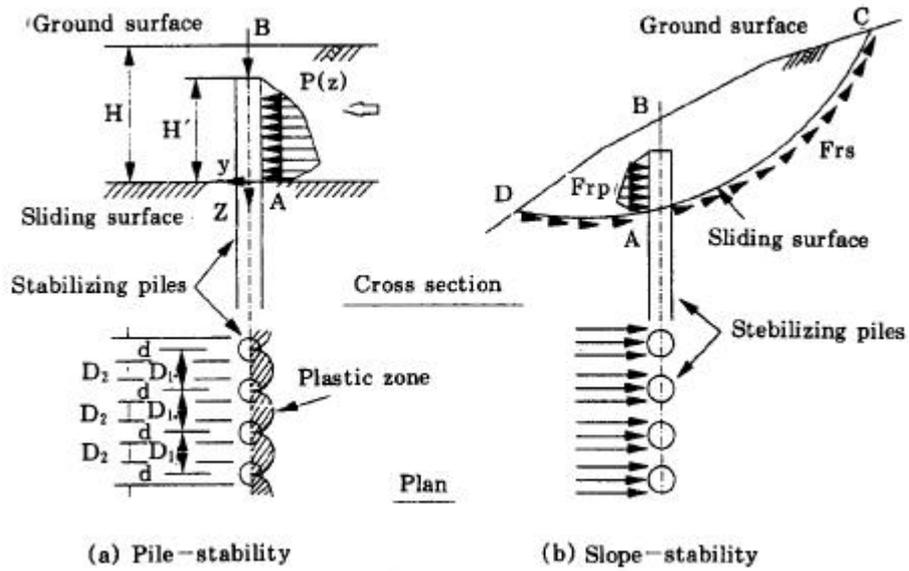
3.1(a)

3.1(b)

가

H

가



3.1

가

3.1

가
가

가

3.1(a)

CADBC

F_d

F_r

AB

F_{rp}

CAD

, A

D

F_{rs}

가

(

3.1(b)

ABCA

ABDA)가

가

가

AD

$(F_s)_{slope}$

$$(F_s)_{slope} = \frac{F_r}{F_d} = \frac{F_{rs} + F_{rp}}{F_d} \quad (3.1)$$

$$(F_s)_{slope} = \frac{M_r}{M_d} = \frac{M_{rs} + M_{rp}}{M_d} \quad (3.2)$$

M_r

, M_d

, M_{rs}

DAC

, M_{rp}

AB

(3.1)

(3.2)

F_{rs}, F_d

M_{rs}, M_d

, F_{rs} M_{rs}

F_{rs} M_{rs} 가

$$(3.1) \quad (3.2)$$

3.2

3.1(a)

$P_{mi}(\bar{z})$

$$E_p I_p \frac{d^4 y_{li}}{d\bar{z}^4} = P_{mi}(\bar{z}) - E_{Sli} y_{li} \quad (-H' \leq \bar{z} \leq 0) \quad (3.3)$$

$$E_p I_p \frac{d^4 y_{2i}}{d\bar{z}^4} = - E_{S2i} y_{2i} \quad (\bar{z} > 0)$$

$\bar{z} = (z - H)$, i

z

, H

H'

, L_p

, y_{li} y_{2i}

, $E_p I_p$

, E_{Sli}

E_{S2i}

P

1

$$z \quad f_{li} + f_{2i} \bar{z} \quad (3.3)$$

$$y_{li} = e^{-\beta_{li}\bar{z}} (a_{li} \cos \beta_{li}\bar{z} + a_{2i} \sin \beta_{li}\bar{z}) + e^{\beta_{li}\bar{z}} (a_{3i} \cos \beta_{li}\bar{z} + a_{4i} \sin \beta_{li}\bar{z}) + (f_{li} + f_{2i}\bar{z}) E_{Sli} \quad (3.4)$$

$$y_{2i} = e^{-\beta_{2i}\bar{z}} (b_{li} \cos \beta_{2i}\bar{z} + b_{2i} \sin \beta_{2i}\bar{z}) + e^{\beta_{2i}\bar{z}} (b_{3i} \cos \beta_{2i}\bar{z} + b_{4i} \sin \beta_{2i}\bar{z})$$

$a_{li}, a_{2i}, a_{3i}, a_{4i}, b_{li}, b_{2i}, b_{3i}, b_{4i}$

(가),

(가),

(가)

(가)

4

$$\beta_{li} = \sqrt[4]{E_{Sli}/4E_p I_p}$$

$$\beta_{2i} = \sqrt[4]{E_{S2i}/4E_p I_p}$$

$(F_s)_{pile}$

σ_{allow}

σ_{max}

$$(F_S)_{pile} = \sigma_{allow} / \sigma_{max} \quad (3.5)$$

가

$$(F_S)_{pile} = \tau_{allow} / \tau_{max} \quad (3.6)$$

, τ_{allow} , τ_{max} 1

3.3

가

가

가

가

0

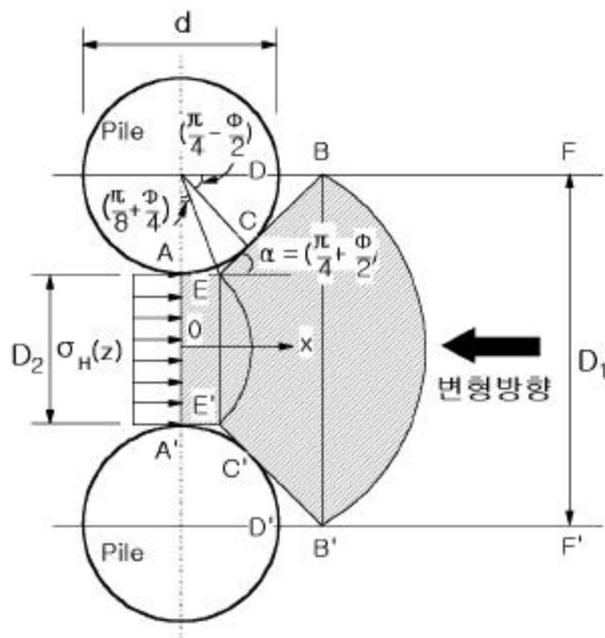
가

가

1

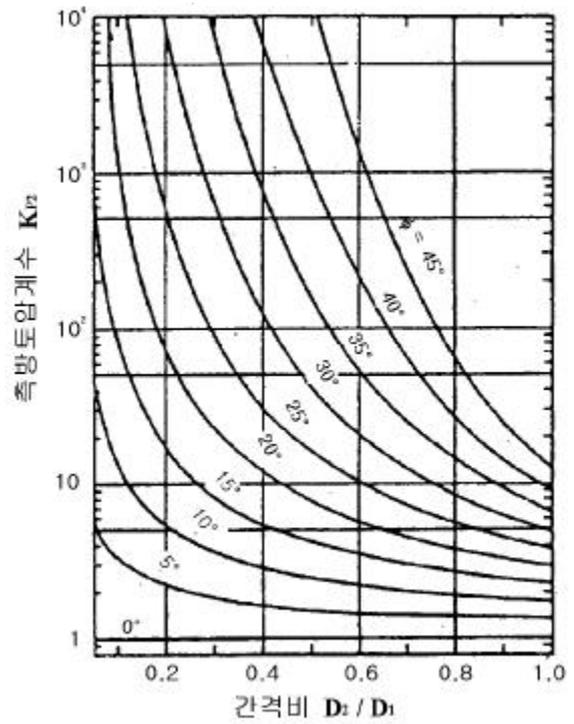
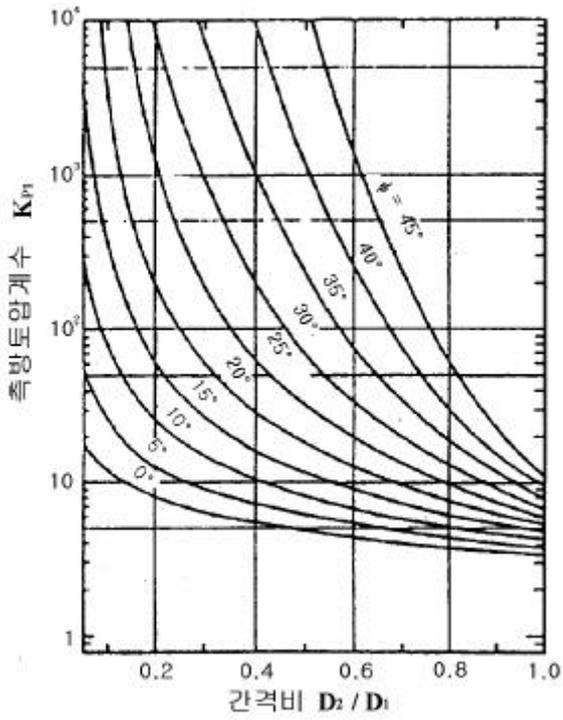
3.1(a)

3.2



3.2

()



3.3

K_{p1} K_{p2} ()

(3.9) K_{p2} (3.8) $\phi = 0$

K_{p1}

(3.8a) $\phi = 0$

(3.9a) , K_{p2}

(3.8b)

(3.8) (3.9)

3.3

D_1 D_2

D_2/D_1

ϕ

3.3

K_{p1} K_{p2}

가

0

(3.7)

가

가

가

$\alpha_m (0 < \alpha_m < 1)$

(3.10)

$$p_m(z) = \alpha_m \times p(z)$$

(3.10)

가

α_m

가

1

α_m

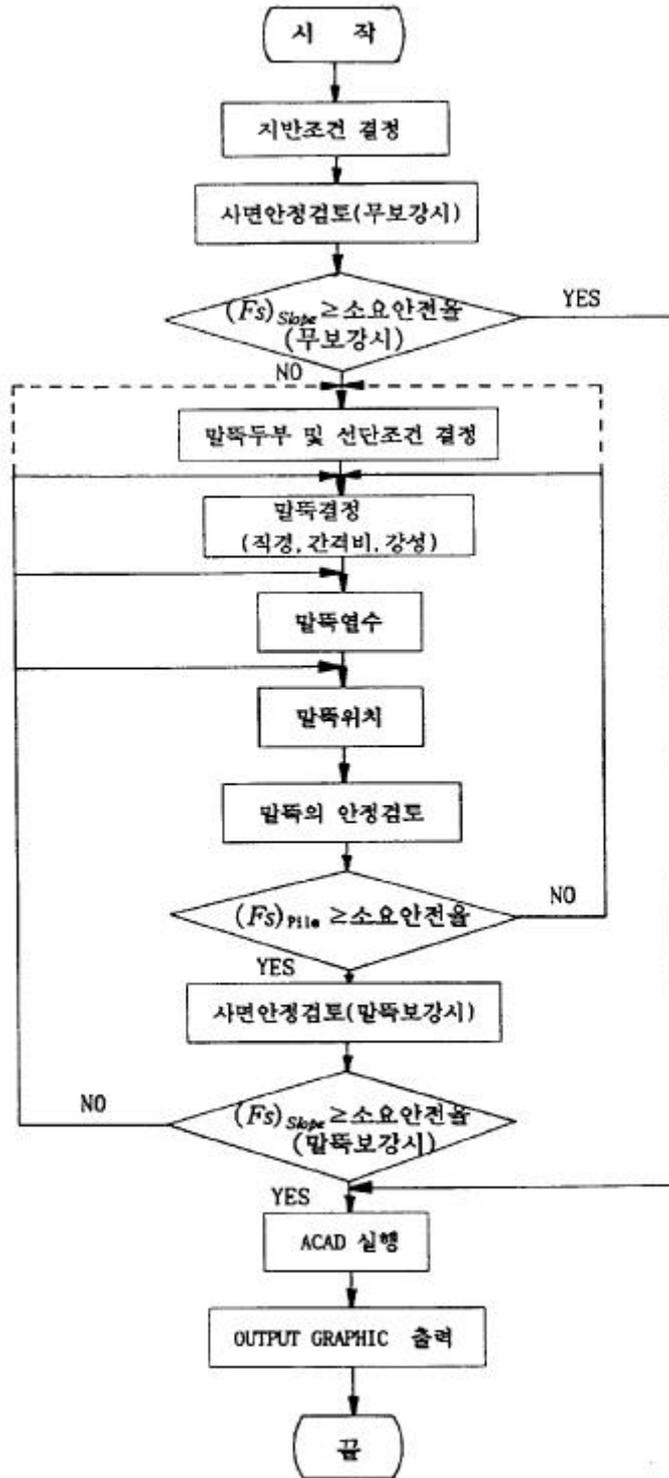
3.4 SPILE

SPILE(Stabilizing Piles to Control Landslide)

(: 94-01-12-2970).

SPILE

가 가



3.4 SPILE

가 ()

가 , ,

3.4 SPILE

가

가

가

가 가

4가

capping

()

3.4 feed

back

1.1 1.3

1.0,

CAD

GRAPHIC

4.

4.1

가

가

가

가

4.1

가
Girder가

가
Girder

가

1991).

(3 ,

4.2

가

가

가

4.1

가

(

)

()

4.1(b)

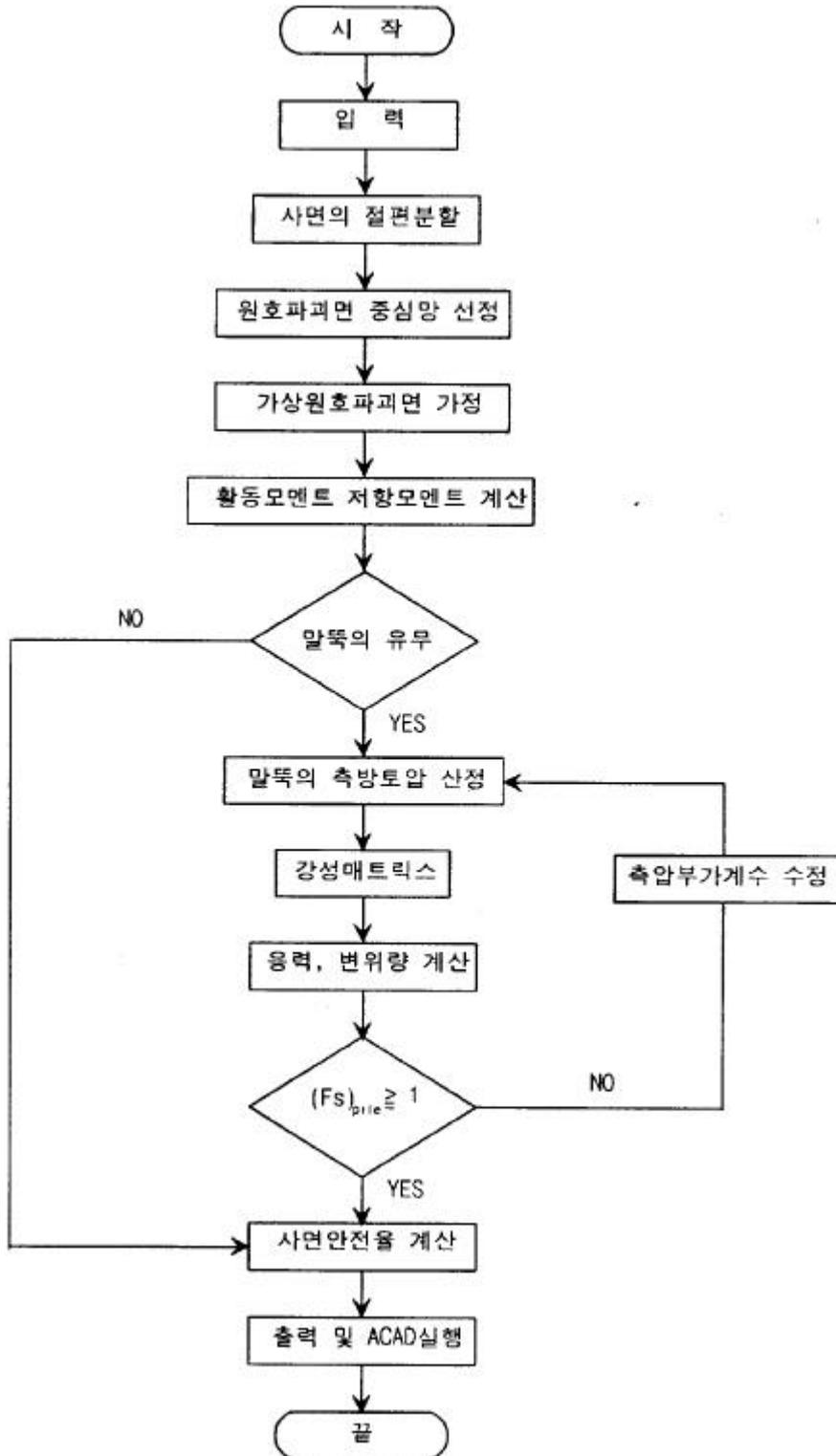
4.1(a)

4.3 CHAMP

CHAMP(CHUNG-ANG ABUTMENT PILES)

가

(Landing pier)



4.2 CHAMP

가

가

4.2 CHAMP

가

, 가

가

가

가

가

Matrix

가

가

가

가

가

가

가

5. Windows

SLOPILE

5.1 SLOPILE

CHAMP SPILE

SLOPILE

(Fellenius, Bishop

)

가

SLOPILE

5.1

가

가

가

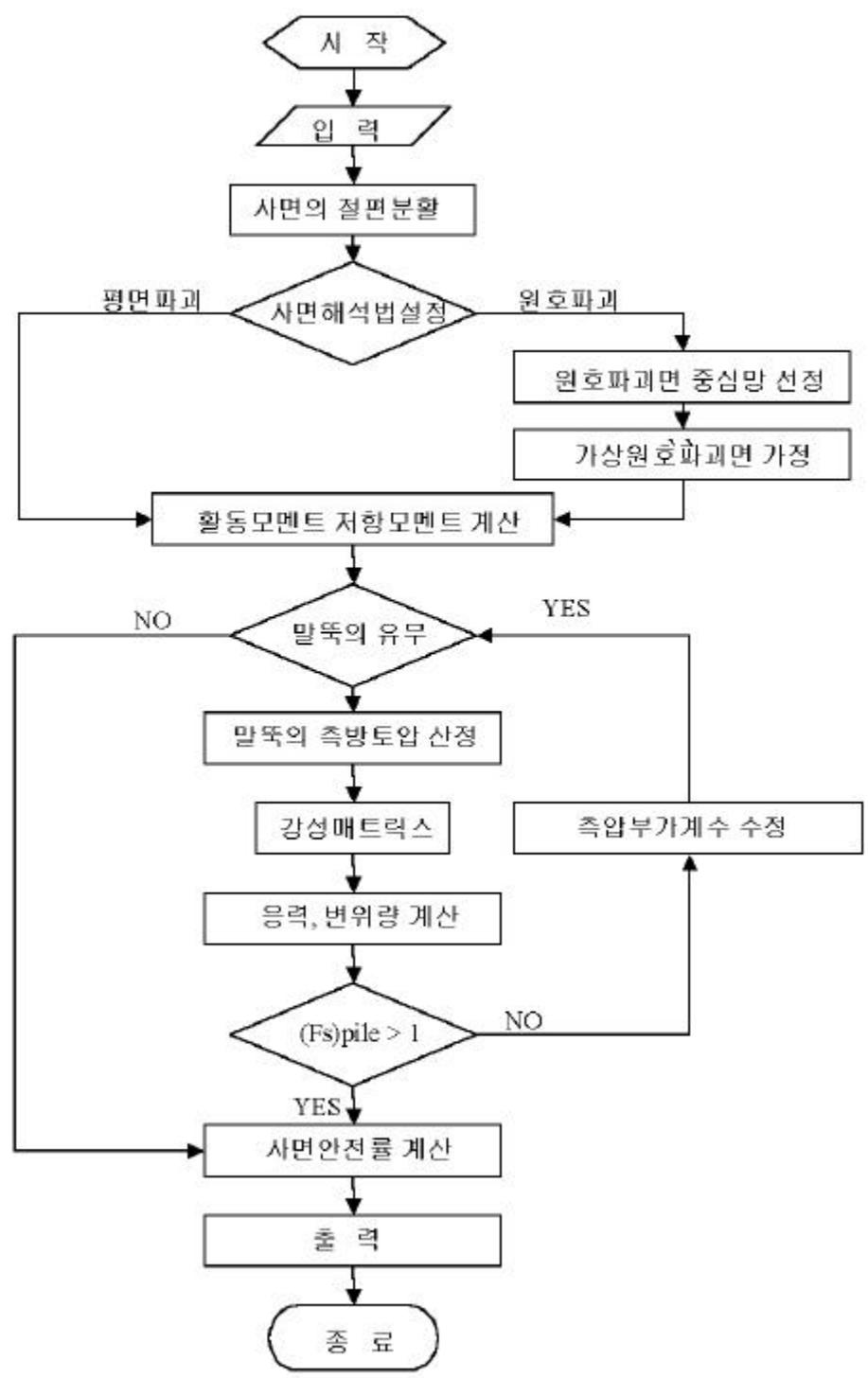
가

가

가

가

가
가
가
가



5.1 SLOPILE

가
가

가

5.2 SLOPILE

SLOPILE Windows
(Multitasking)

Windows

Dos

CHAMP, SPILE

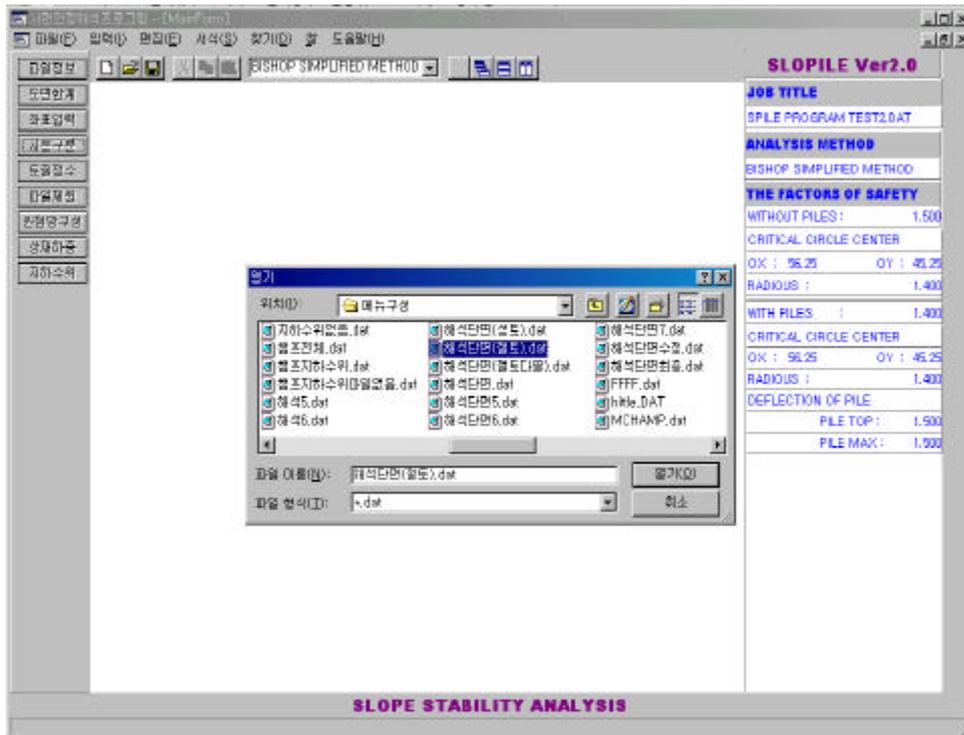
SLOPILE

5.2

5.12

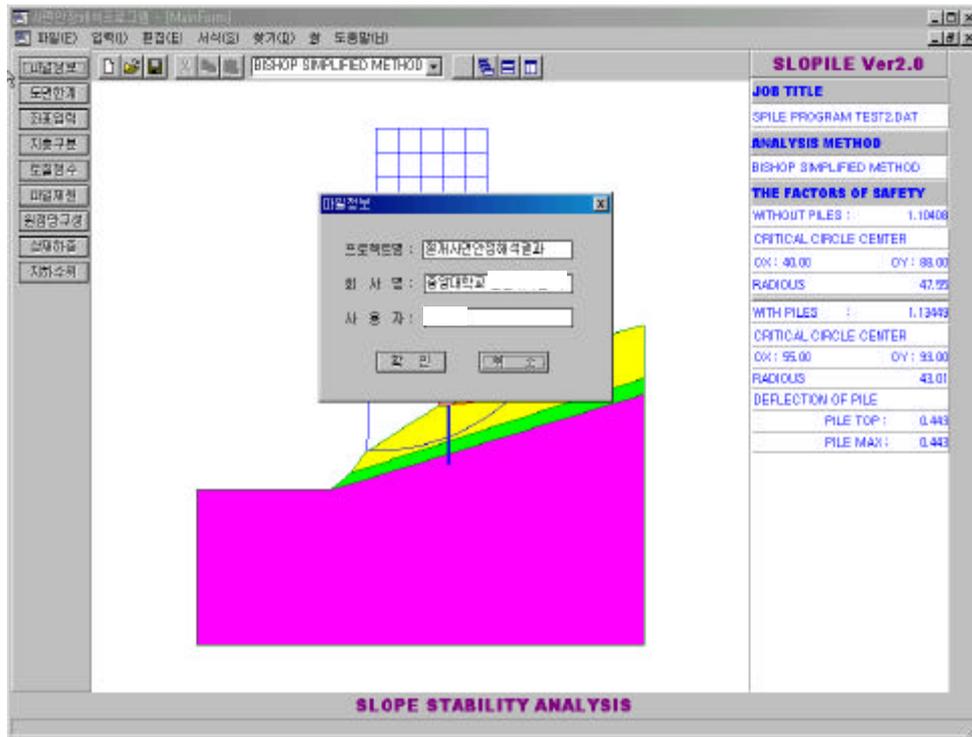
SLOPILE

(1)



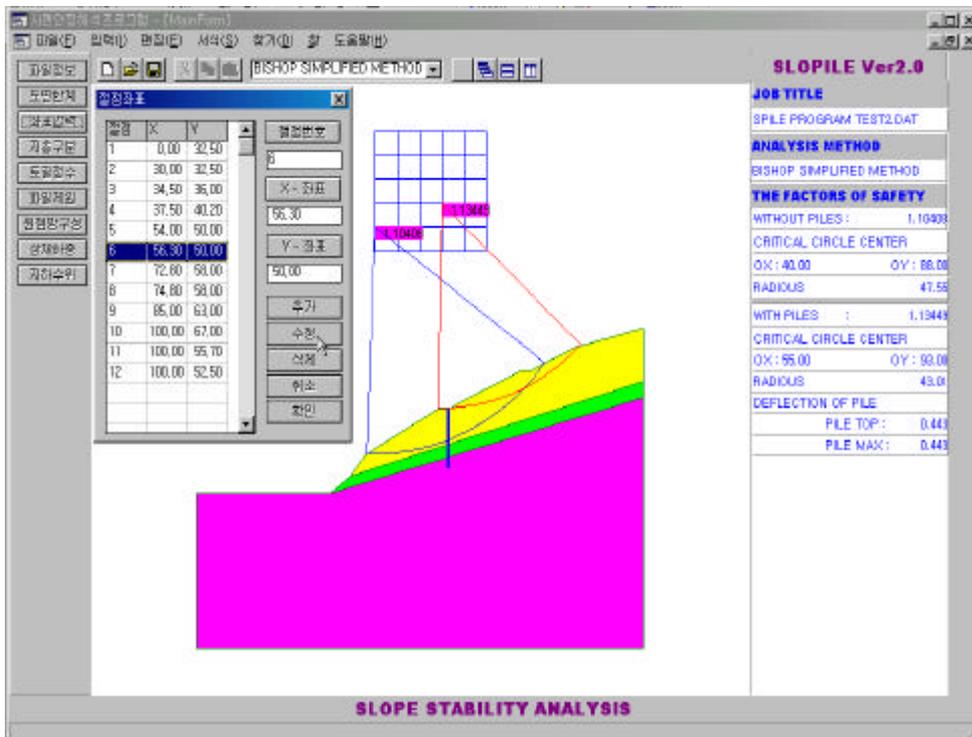
5.2

(2)



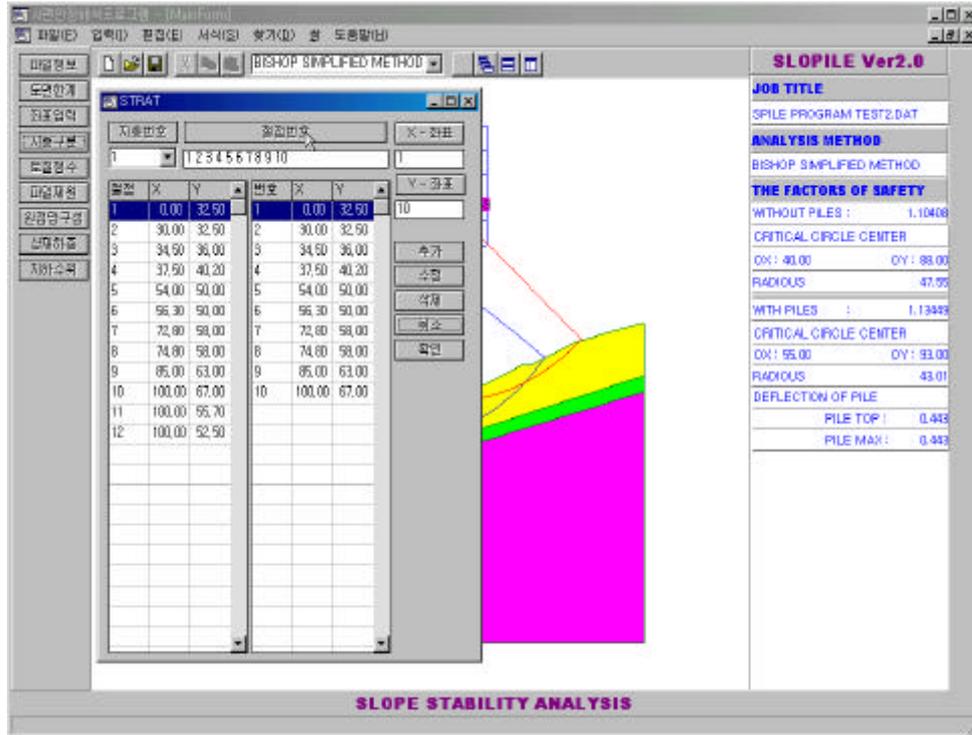
5.3

(3)



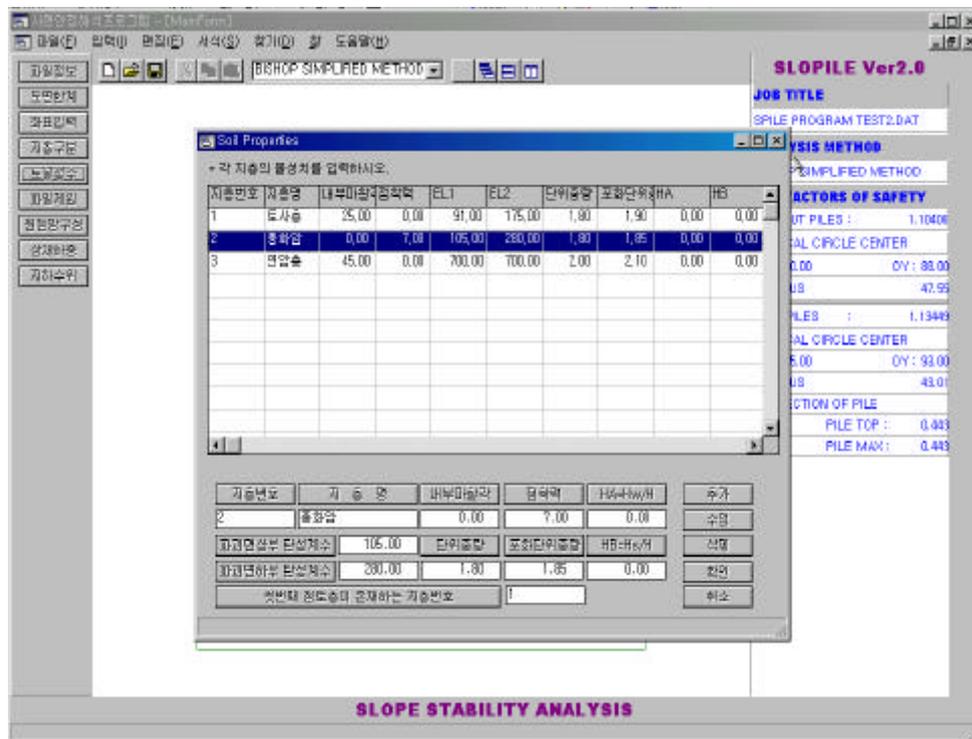
5.4

(4)



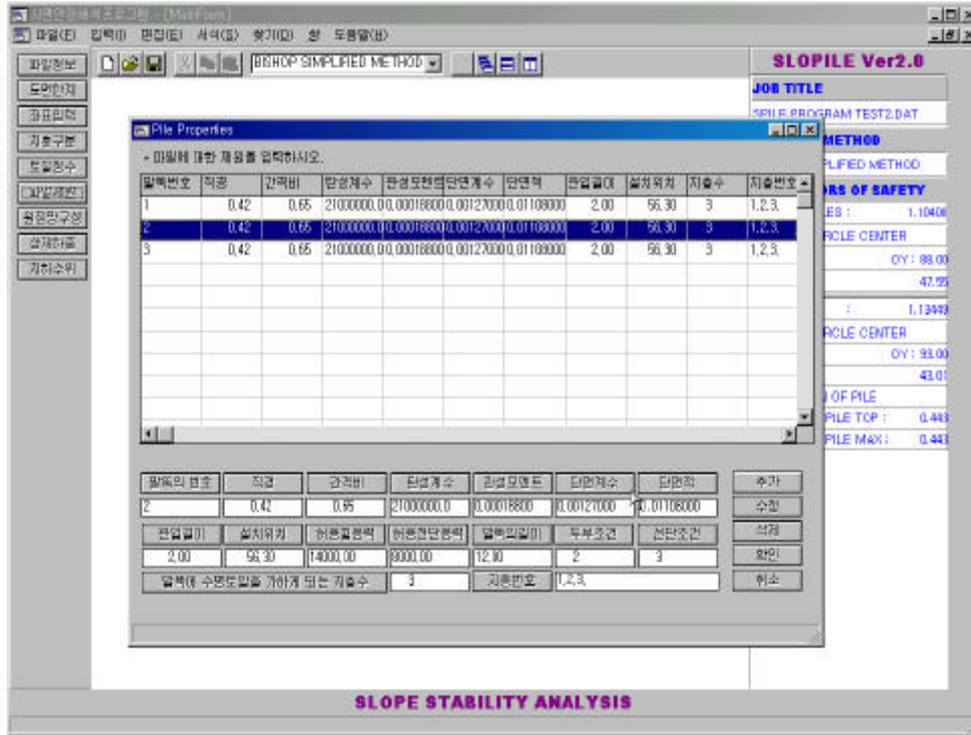
5.5

(5)



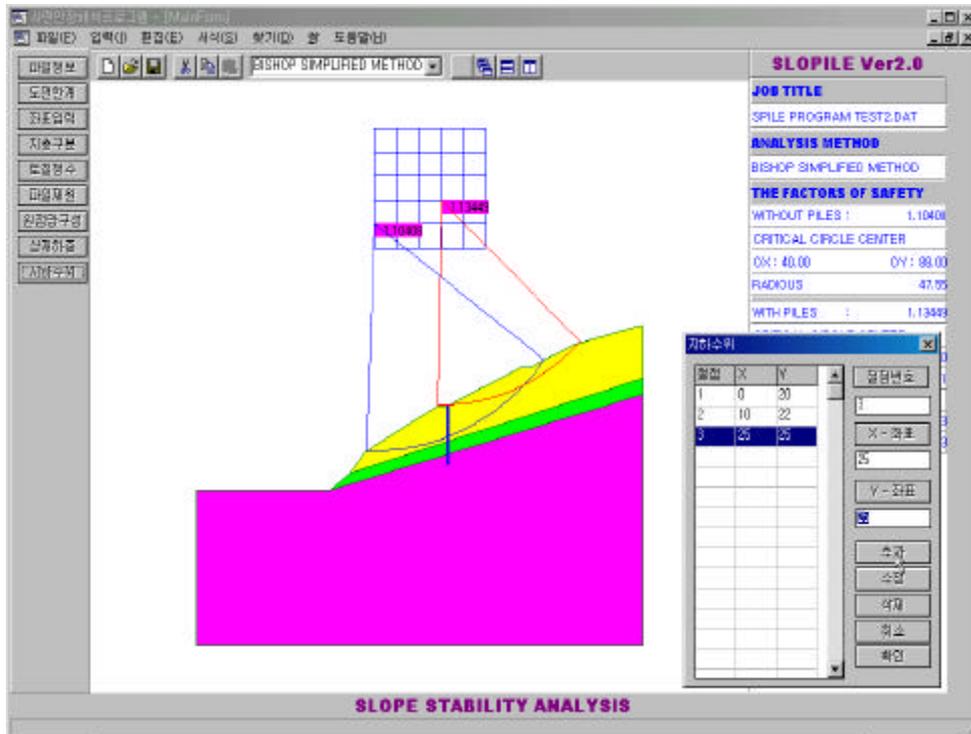
5.6

(6)



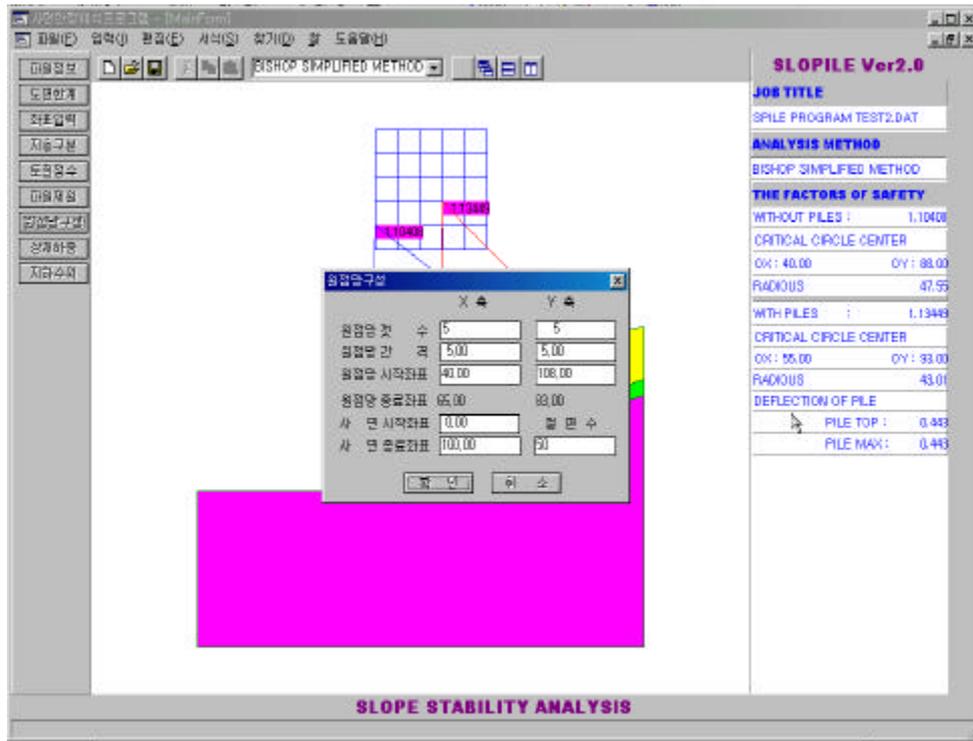
5.7

(7)



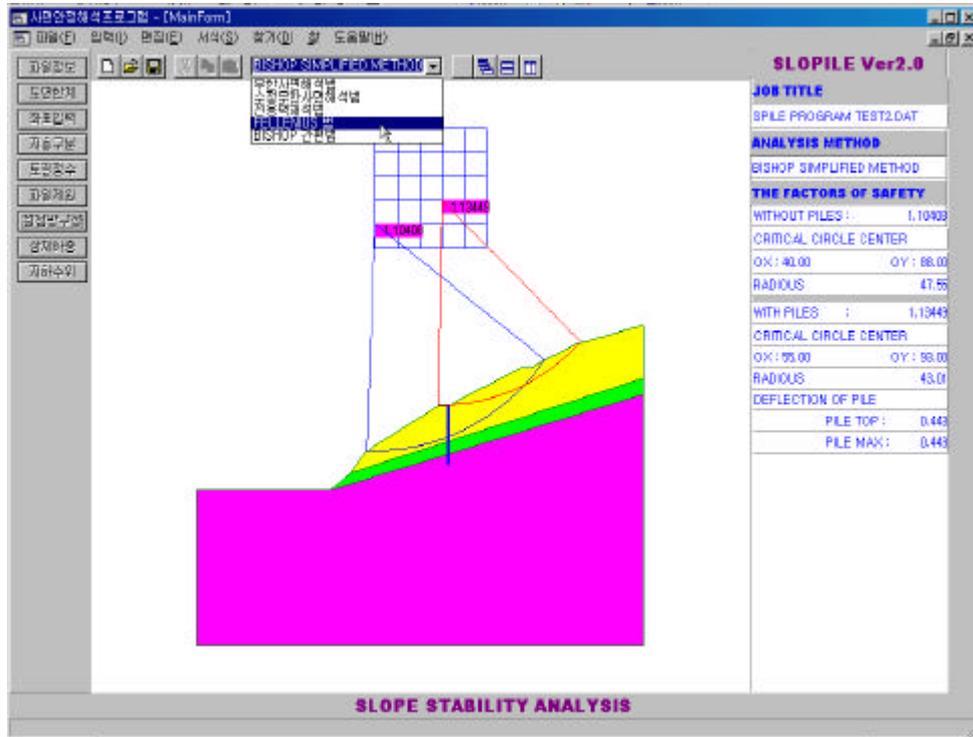
5.8

(8)



5.9

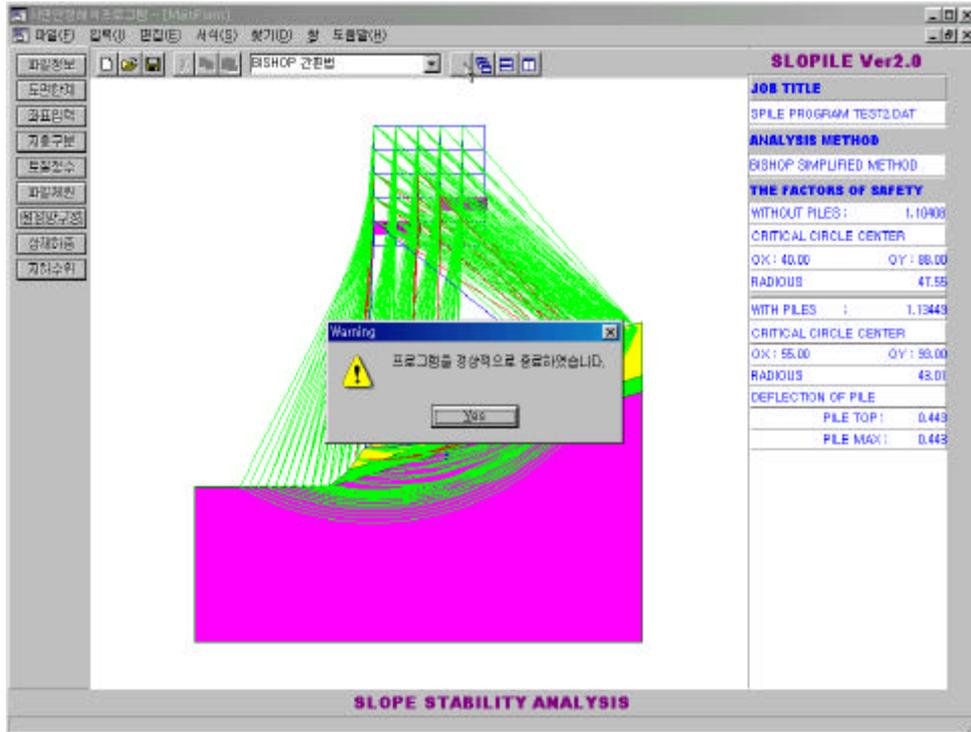
(9)



5.10

(10)

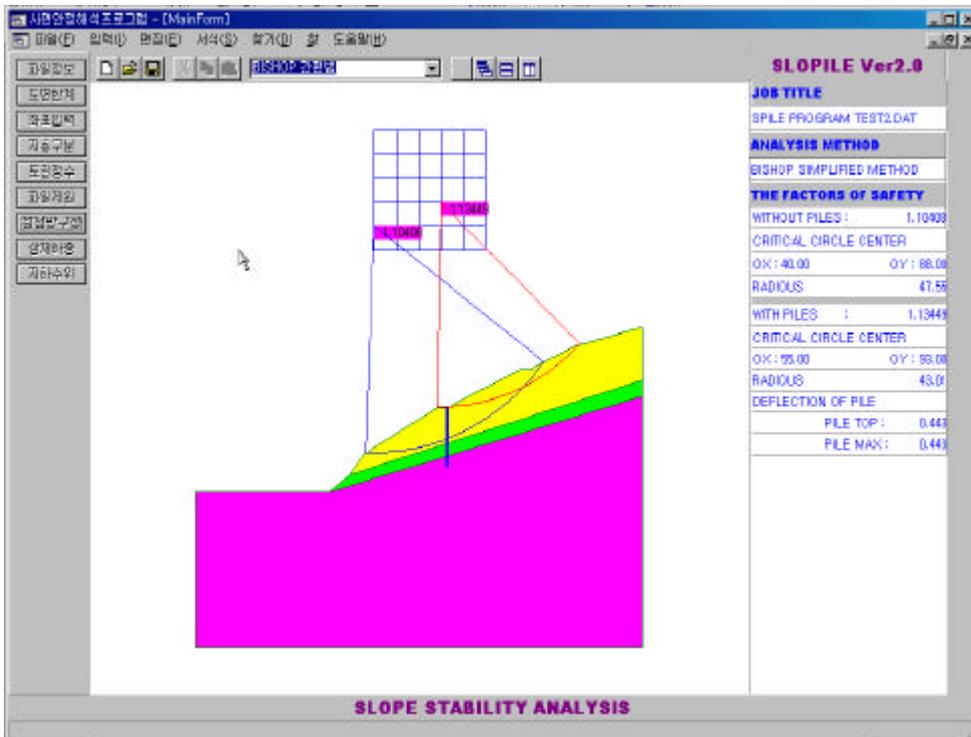
:



5.11

(11)

:



5.12

6. SLOPILE

6.1

6.1.1

6.1

가

6.1 20m
6m 가 ,

6.1

27 °

1.8 t/m³ 1.9 t/m³

25 °

1.7 t/m³ 1.8 t/m³

가 2.5 t/m² ,

1.65 t/m³ 1.75

t/m³

35 °

2.0

t/m³ ,

2.1 t/m³

가

가

가

가

가

(Fellenius

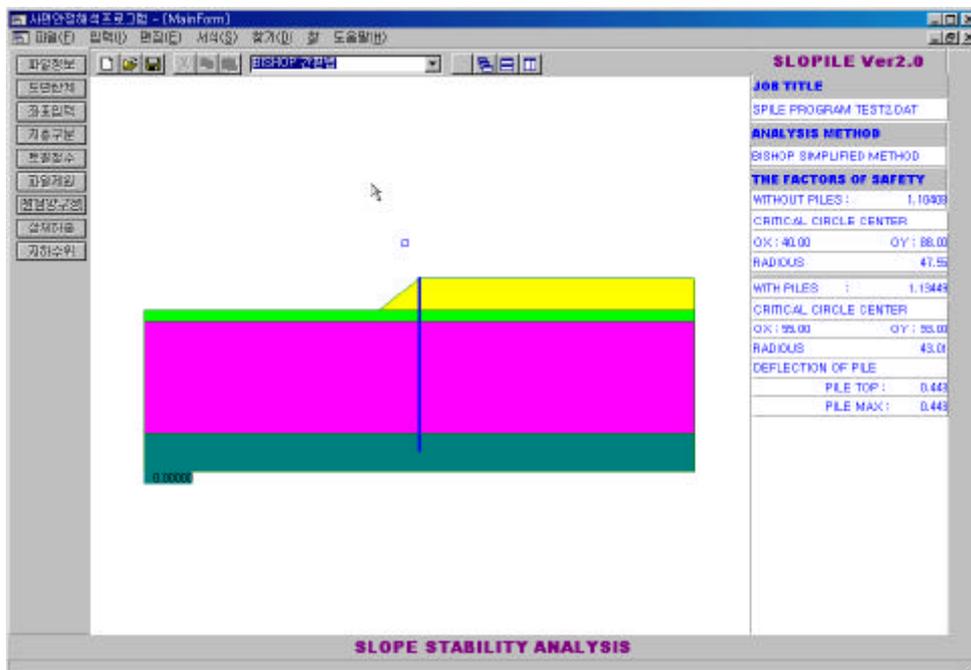
Bishop)

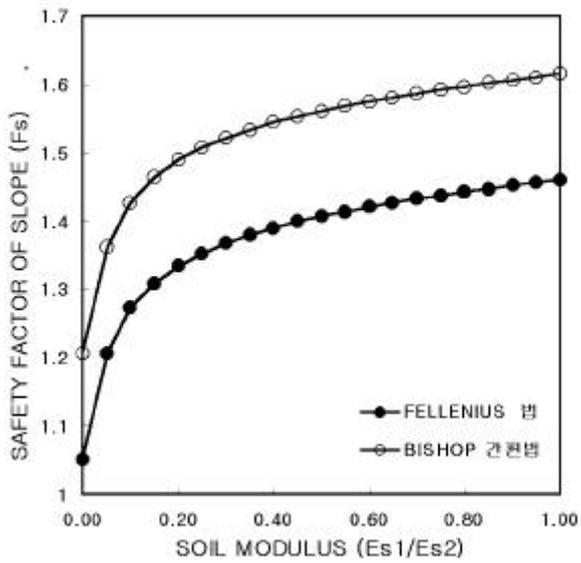
H- (H- 300 × 300 × 10 × 15)

420mm

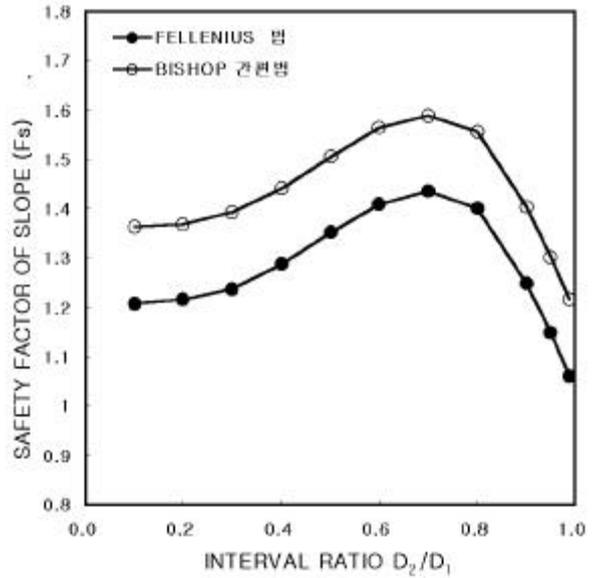
1.25m

D_2 / D_1 0.65





6.2



6.3

1)

2) H-Pile $2.1 \times 10^6 \text{ kg/cm}^2$

3) H-Pile 1400 kg/cm^2 800 kg/cm^2

4)

5) E_s E_{s1} 91 t/m^2
 $37.5 \text{ t/m}^2 (= 15c_u)$ $100 \text{ t/m}^2 (= 40c_u)$
 350 t/m^2

6.1.2

1)

6.2

가

E_{s1}, E_{s2} (E_{s1}/E_{s2})

가 가

가

E_{s1} E_{s2}

가

Marche & Lacroix가

E_{s1}

91 t/m^2

$15 c_u$

37.5 t/m^2

6.2

Fellenius

1.05, Bishop

1.21

1.04, 1.19

가

가

E_{s1}

가

가

E_{s1}

가

가

Marche & Lacroix

Poulos

2)

(D_2/D_1)

6.3

, D_2/D_1

0.1 0.99

6.3

가 가

가 가

0.70

가

가

0.6 0.8

3)

6.4

6.1

5

가

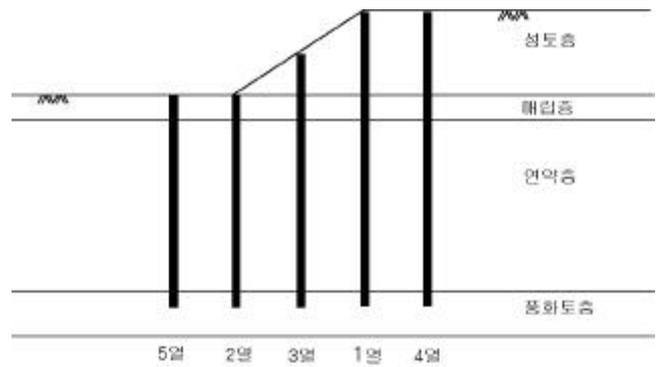
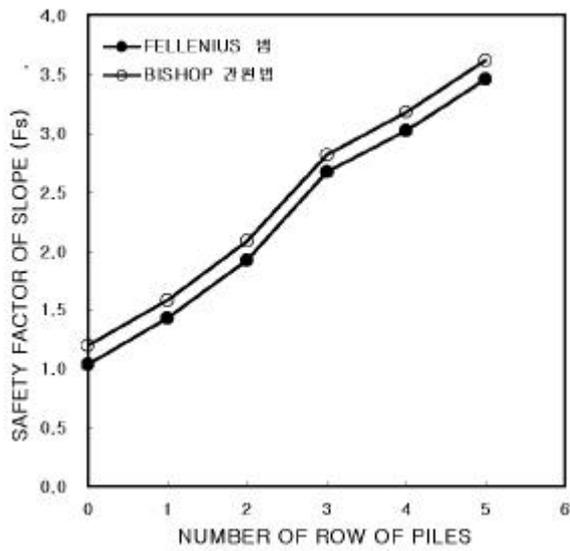
가

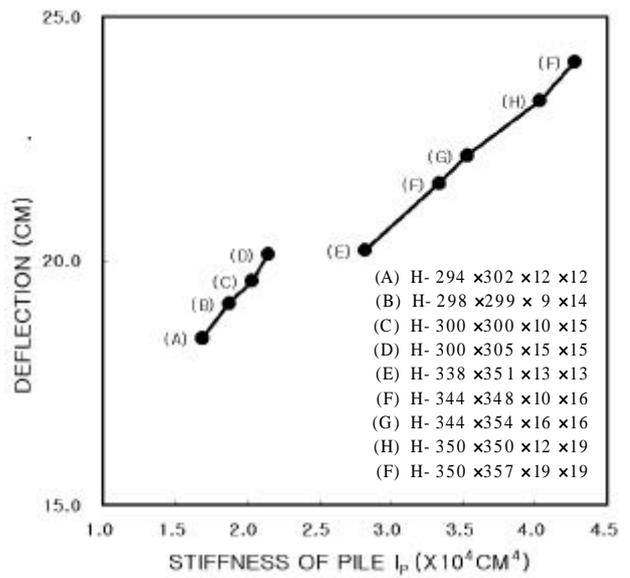
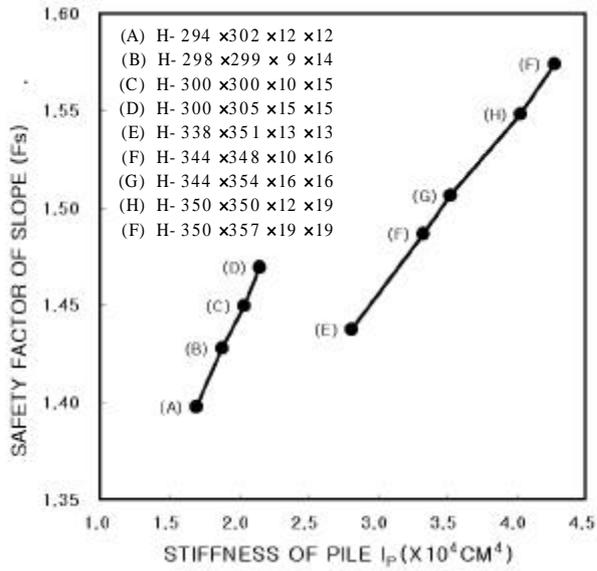
가

가

1.3

2





4)

가

가

6.5

가

(H - 300 × 300 H - 350 × 350)
가

가

6.6

가

가

6.1.3

1)

6.7

()

가 가

가

6.8

E_{s1}

6.8(a)

51.8cm가

6.8(b)

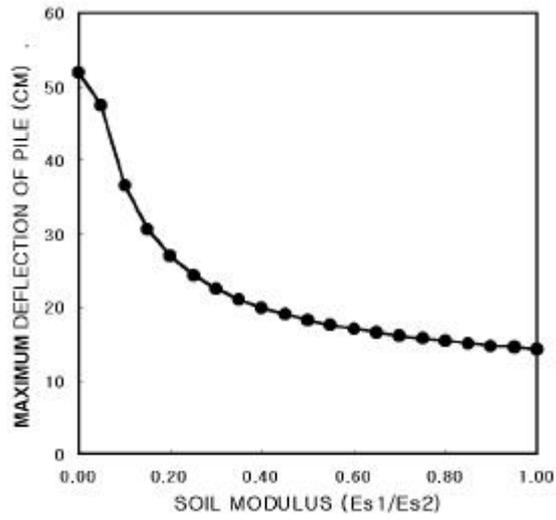
Marche & Lacroix가

E_{s1}

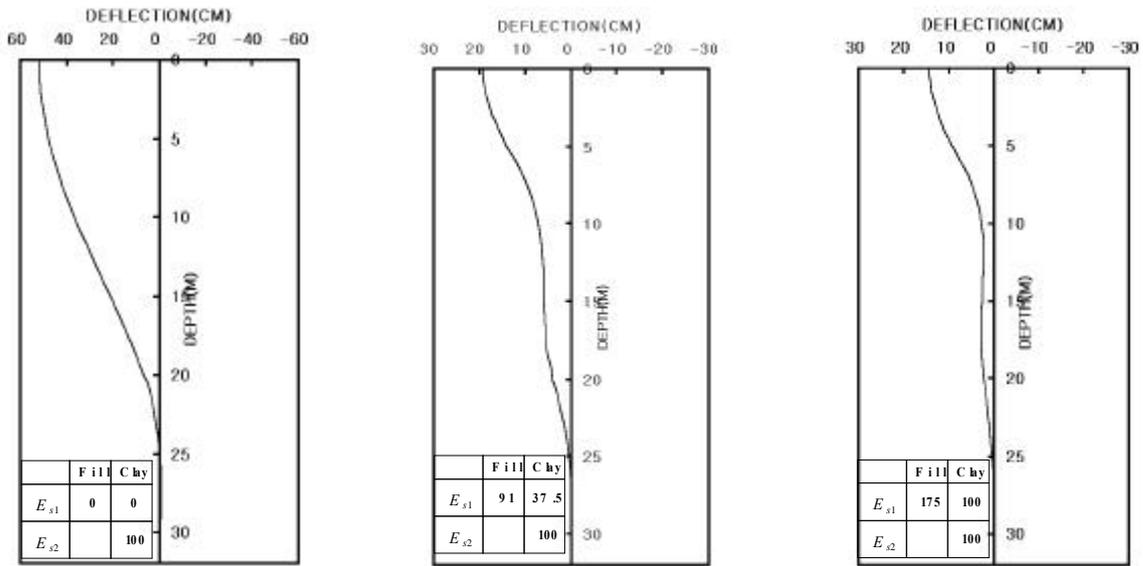
91 t/m^2

$15 c_u$

37.5 t/m^2



6.7



6.8

19.1cm가

6.8(c)

E_{s1}

E_{s2}

14.3cm가

6.8

6 10m

가

가

2)

6.9

가

4가

가

6.1

6.9(a)

가

가

가

가

가

가

6.9(b)

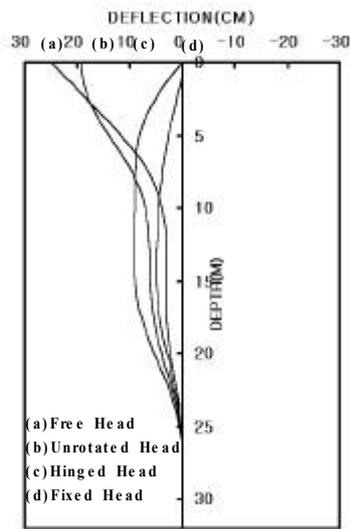
4m

7m

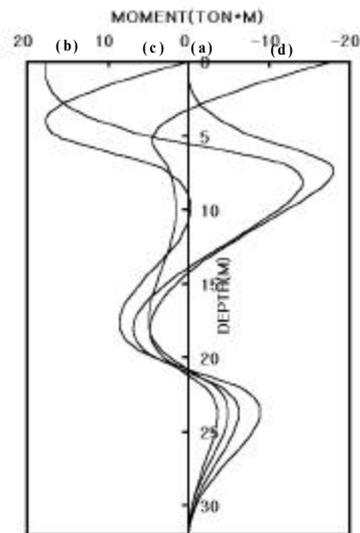
가

6.1

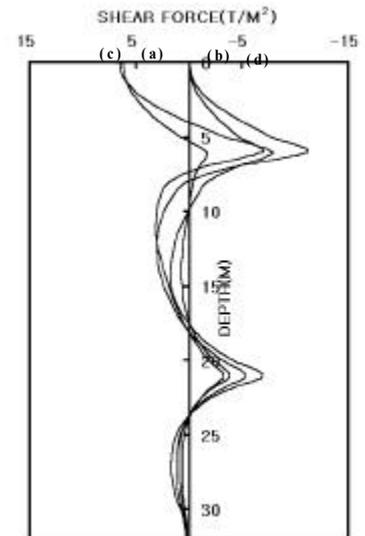
	(m)	(m)	(m)	(m)	(m)	(m)	(m)
(cm)	0	19.131	0	0	0	24.947	0
(cm)	0	19.131	13	9.043	0	24.947	14
(t · m)	0	17.78	4	17.78	7	17.78	0
(t/m ²)	6	11.19	21	6.9	6	6.877	0



(a)



(b)



(c)

6.9

6.9(c)

6m, 6m, 21m

6.2

6.2.1

6.10

가

6.10

2m

가

25 °,

가 7.0 t/m²

45 °

1.8 t/m³ 1.9 t/m³ ,
 1.8 t/m³ 1.85 t/m³ ,
 2.0 t/m³, 2.1 t/m³

20m

1

H- (H- 300 × 300 × 10 × 15)

420mm

2.0m

1.25m

D_2/D_1 0.65

6.1

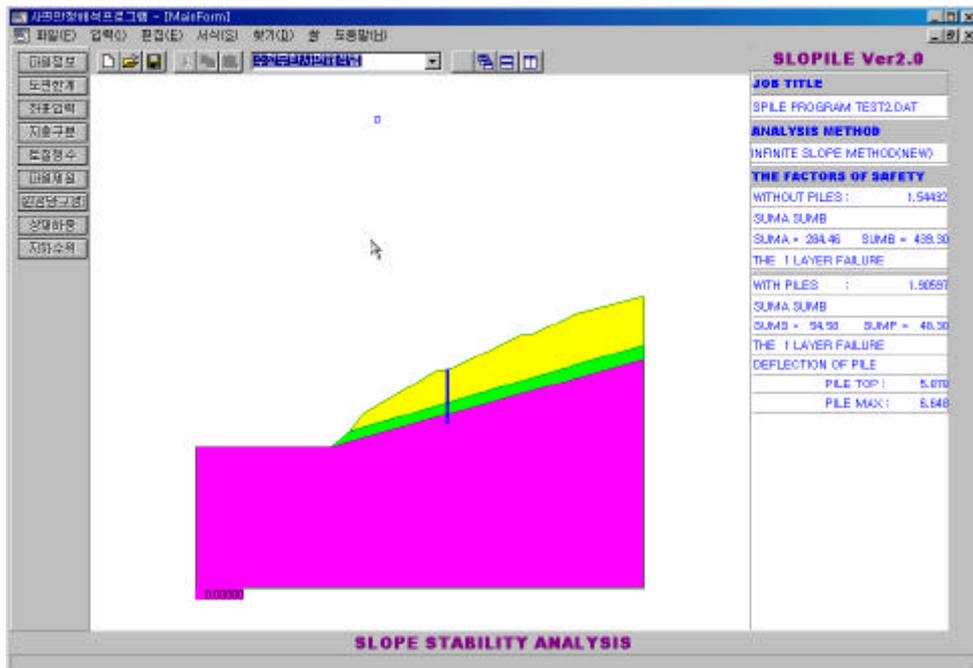
E_s

E_{s1} 91 t/m²

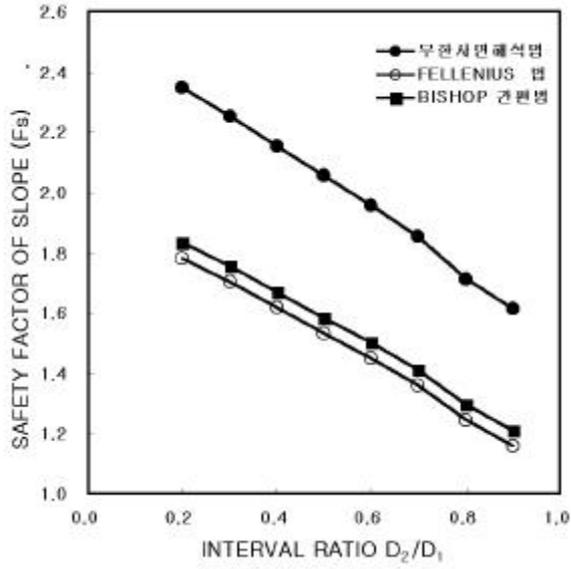
105

t/m² (= 15 c_u) 280 t/m² (= 40 c_u)

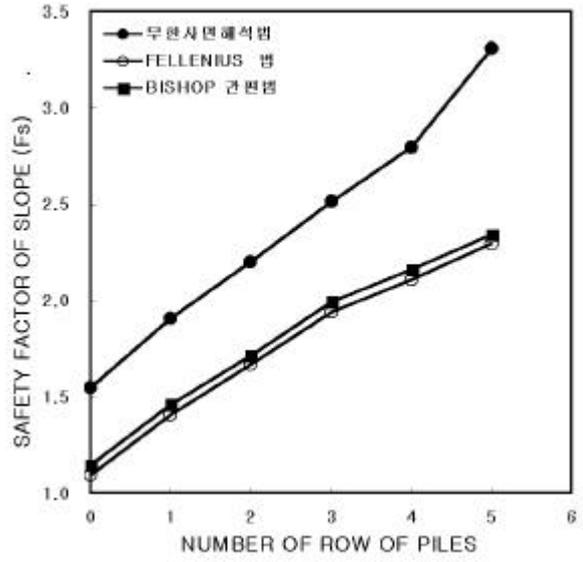
700 t/m²



6.10



6.12



6.13

3)

6.9

가

가

가

가

6.10

가

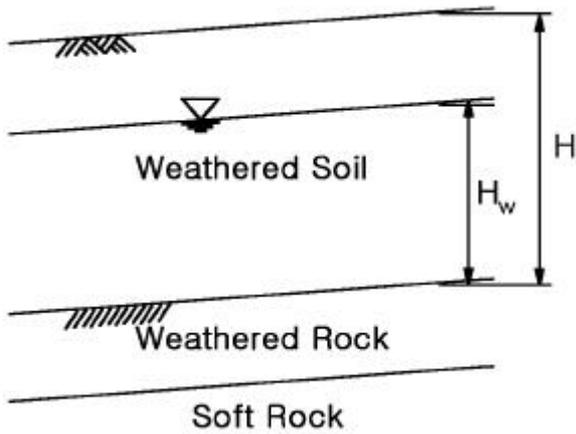
가

6.14

H

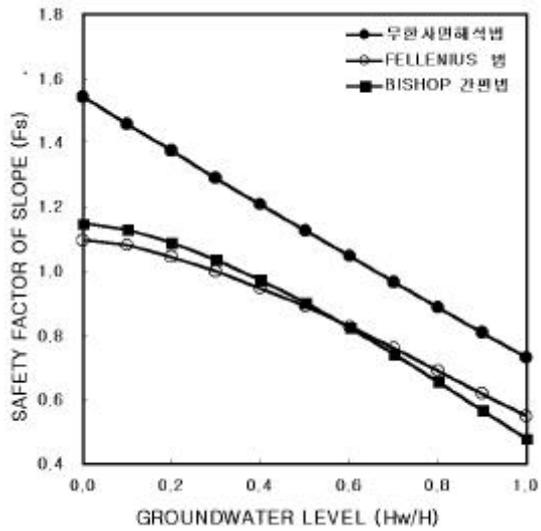
H_w

H_w/H



6.14

(H_w/H)



6.15

가 $H_w/H = 1$ 가 0

6.15 H_w/H

가 0 1.54, Fellenius 1.10, Bishop 1.15

가 H_w/H 가 1

, Fellenius , Bishop 0.73, 0.55, 0.48

, 1.1 H_w/H 가 0.7

H_w/H 가 0.4

Fellenius Bishop H_w/H 가 0.6

Bishop Fellenius 가

가

6.2.3

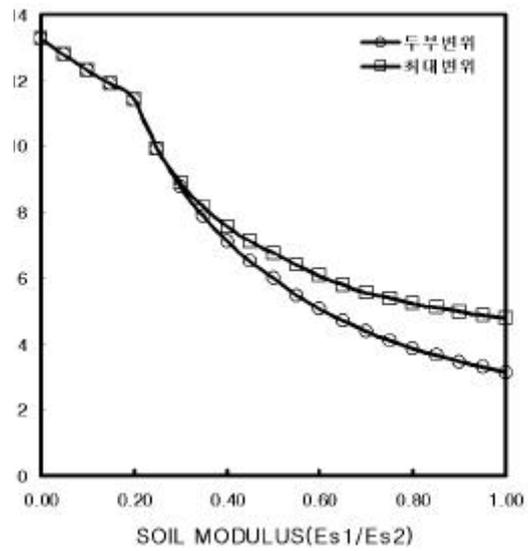
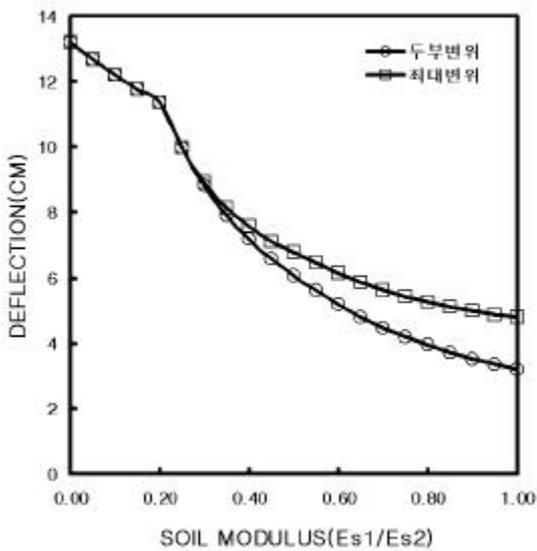
1)

6.16 가 가 0.2

가 0.6

6.17 E_{s1} 0, 91, 175

가



(b)

6.16

가 0/175
 가 91/175
 4.8cm

가 175/175

13.2cm
 5m

6.6cm
 5m

2)

6.18

가

4가

6.2

	(m)		(m)		(m)		(m)	
(cm)	0	5.878	0	0	0	3.86	0	0
(cm)	4	6.648	5	4.198	4	5.957	6	1.912
(t · m)	5	17.78	5	17.78	5	17.78	0	17.78
(t/m ²)	12	8.354	12	5.771	12	7.596	0	7.836

가

6.2

6.18(b)
 가

5m

6.18(c)

12m

7.

가

CHAMP SPILE
 SLOPILE

Bishop

가

Dos

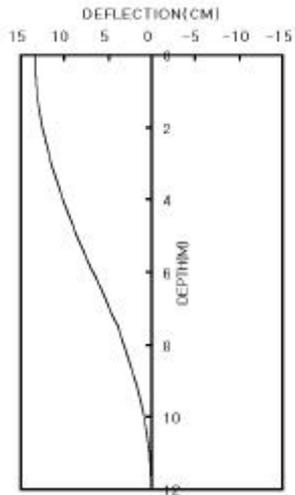
CAD

OS

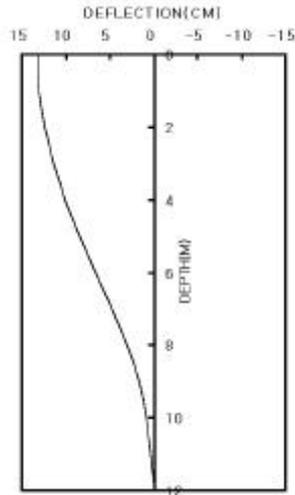
Windows
 SLOPILE

가

가

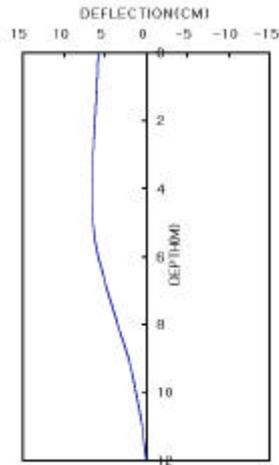


(a)

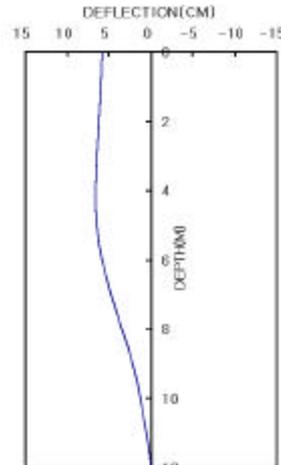


(b)

E_{s1}	0	-
E_{s2}	175	280

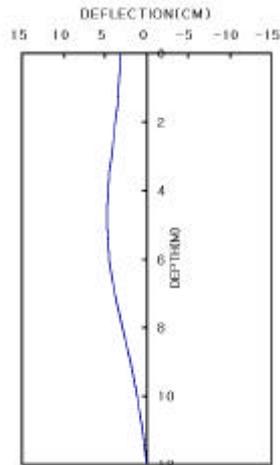


(c)

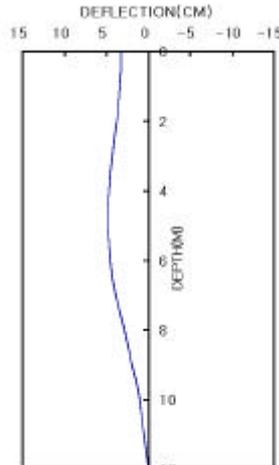


(d)

E_{s1}	91	-
E_{s2}	175	280

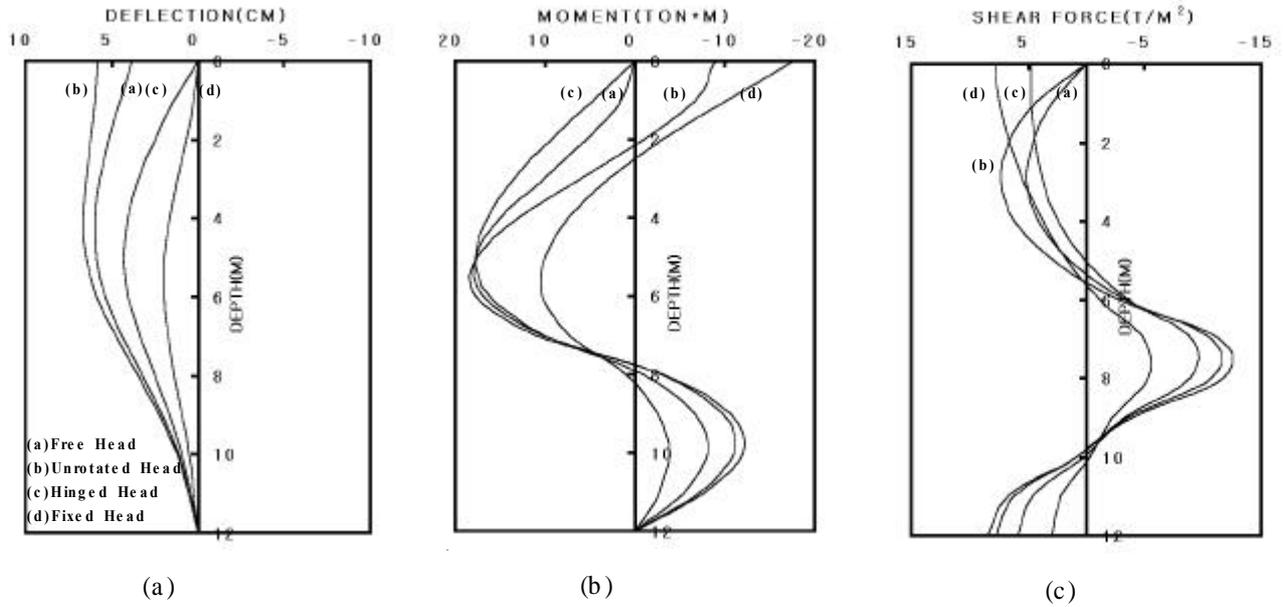


(e)



(f)

E_{s1}	175	-
E_{s2}	175	280



6.18

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